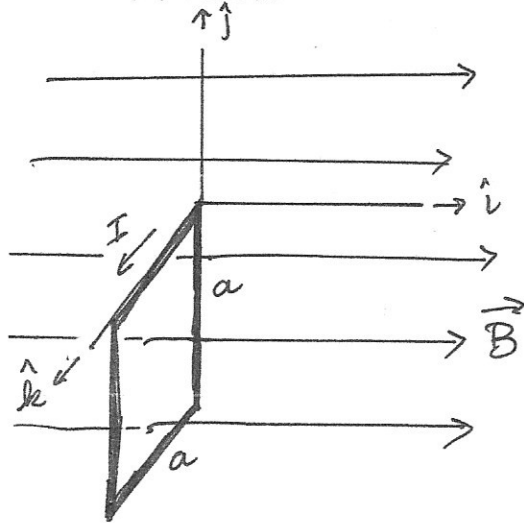


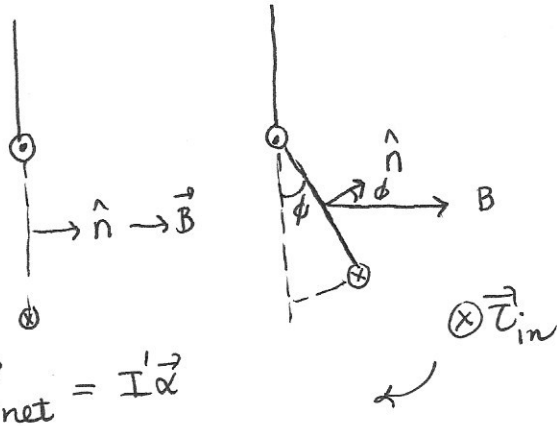
Show all your work for full credit. No scratch paper, note cards, cell phones or other electronic devices are allowed. You have one (1) hour.

**PLEASE BOX YOUR FINAL ANSWER**

1. A single square loop of side  $a$  is in free space (no gravity) hinged along the  $z$ -axis, with one corner at the origin as shown in the picture. The loop has uniformly distributed mass  $M = 4m$  and carries current  $I$  in the sense shown. The loop is immersed in a uniform magnetic field  $\vec{B} = B_0 \hat{i}$ . The loop is displaced from the equilibrium position by a small angle  $\phi$ . Find the period of oscillation,  $T$ . (Recall  $\omega = 2\pi/T$  and that the moment of inertia for a single rod about an axis located at one end is  $I' = \frac{1}{3}ml^2$ ) Your answer may be in terms of  $m$ ,  $I$ , and  $B_0$ .



perspective view



$$\vec{\tau}_{net} = I' \vec{\alpha}$$

$$\vec{\mu} \times \vec{B} = I' \vec{\alpha}$$

$$NI A \hat{n} \times \vec{B} = I' \vec{\alpha}$$

$$I a^2 B \sin \phi = -I' \alpha$$

$$N=1 \quad A=a^2$$

the torque seeks to restore equilibrium, so the acceleration is in the opposite sense

For  $\phi \ll 1$   
 $\sin \phi \approx \phi$

$$I a^2 B \phi = -I' \frac{d^2 \phi}{dt^2}$$

Let  $\phi = A \cos \omega t$

$$\frac{d\phi}{dt} = -A \omega \sin \omega t$$

$$\frac{d^2 \phi}{dt^2} = -A \omega^2 \cos \omega t$$

$$I a^2 B (A \cos \omega t) = +I' (+A \omega^2 \cos \omega t)$$

$$\omega^2 = \frac{I a^2 B}{I'}$$

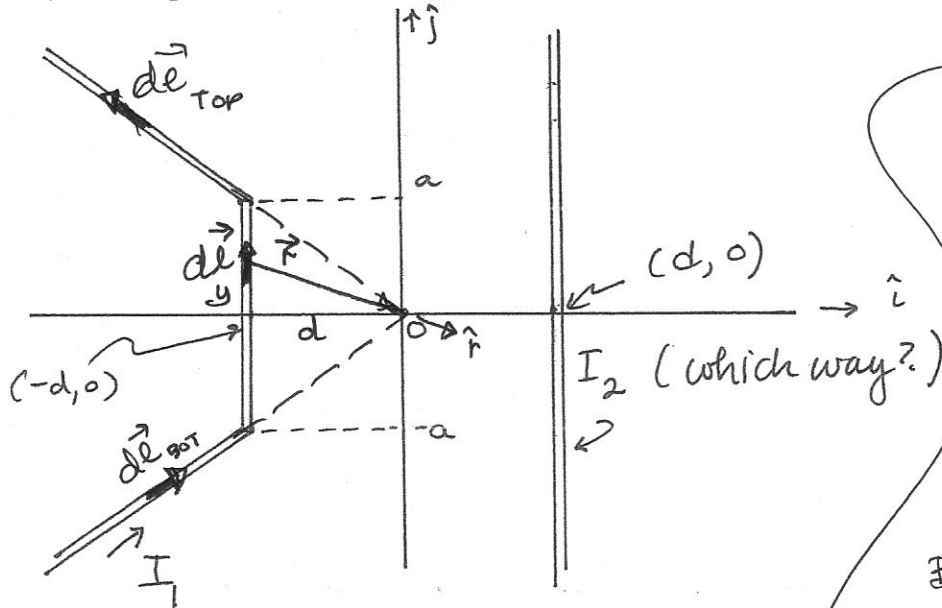
$$\omega^2 = \frac{I a^2 B}{\frac{5}{3} m a^2}$$

$$I' = 2 \left( \frac{1}{3} m a^2 \right) + m a^2$$

$$I' = \frac{5}{3} m a^2$$

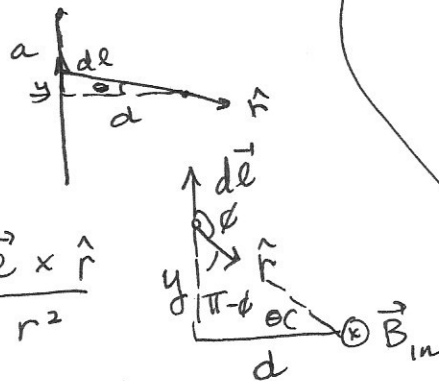
$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{5m}{3IB}}$$

2. A very long wire with current  $I_1$  is bent into three straight sections. It lies in the  $x$ - $y$  plane as shown with the center section of length  $2a$  parallel to the  $y$ -axis and centered at  $x = -d$ . An infinitely long straight wire, also in the  $x$ - $y$  plane is parallel to the  $y$ -axis and crosses the  $x$ -axis at  $x = +d$  as shown in the diagram. If the magnetic field  $\vec{B}$  at the origin is exactly zero, what is the current  $I_2$ ? (You must use the Biot-Savart law for wire 1, but may use Ampere's law for wire 2.) Your answer should be in terms of  $d$ ,  $I_1$ , and  $a$



$$\vec{d\vec{e}}_{\text{bot}} \times \hat{r} = 0$$

$$\vec{d\vec{e}}_{\text{top}} \times \hat{r} = 0$$



$$d\vec{B}_1 = \frac{\mu_0 I_1}{4\pi} \frac{d\vec{e} \times \hat{r}}{r^2}$$

$$d\vec{e} = dy \hat{j}$$

$$\vec{B}_1 = \frac{\mu_0 I_1}{4\pi} \int \frac{dy \hat{j} \times \hat{r}}{(d^2 + y^2)}$$

$$|\vec{B}_1| = \frac{\mu_0 I_1}{4\pi} \int \frac{dy \sin(\phi)}{d^2 + y^2} \quad \left\{ \sin \phi = \sin(\pi - \phi) \right\}$$

$$B_1 = \frac{\mu_0 I_1}{4\pi} \int \frac{dy \cos \theta}{d^2 + y^2} \quad \left\{ \sin(\pi - \phi) = \cos \theta \right\}$$

$$y = d \tan \theta; \quad dy = d \sec^2 \theta d\theta$$

$$B_1 = \frac{\mu_0 I_1}{4\pi} \int \frac{d \cos \theta \sec^2 \theta d\theta}{d^2 (1 + \tan^2 \theta)}$$

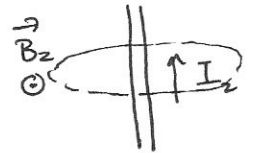
$$B_1 = \frac{\mu_0 I_1}{4\pi d} \int \cos \theta d\theta$$

$$B_1 = \frac{\mu_0 I_1}{4\pi d} \sin \theta \Big|_{\text{limits}}$$

$$\text{but } \sin \theta = \frac{y}{(d^2 + y^2)^{1/2}}$$

$$B_1 = \frac{\mu_0 I_1}{4\pi d} \left( \frac{y}{(d^2 + y^2)^{1/2}} \Big|_{-a}^a \right)$$

$$B_1 = \frac{\mu_0 I_1 2a}{4\pi d (d^2 + a^2)^{1/2}}$$



$$\oint \vec{B}_2 \cdot d\vec{s} = \mu_0 I_2$$

$$B_2 \oint ds = \mu_0 I_2$$

$$B_2 2\pi d = \mu_0 I_2$$

$$B_2 = \frac{\mu_0 I_2}{2\pi d}$$

$$\vec{B}_{\text{net}} = 0$$

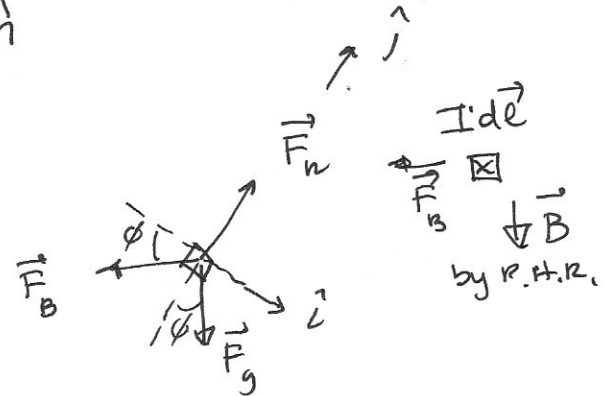
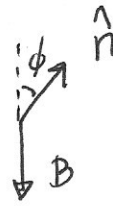
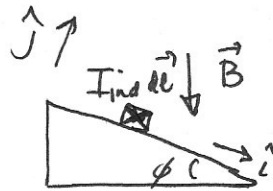
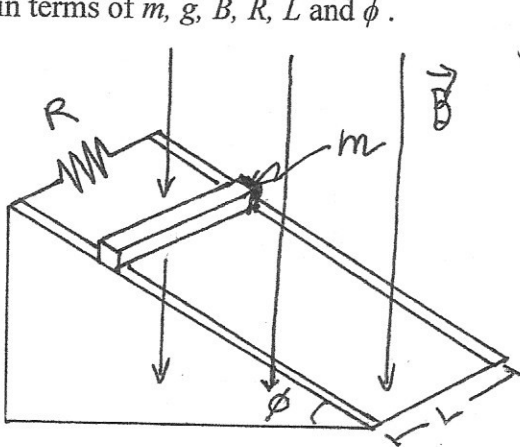
$$\vec{B}_1 + \vec{B}_2 = 0$$

$$\text{+ out } -B_1 + B_2 = 0$$

$$\frac{\mu_0 I_1 2a}{4\pi d (d^2 + a^2)^{1/2}} = \frac{\mu_0 I_2}{2\pi d}$$

$$I_2 = \frac{I_1 a}{(d^2 + a^2)^{1/2}}$$

3. A metal bar of mass  $m$  is released from rest on frictionless conducting rails. The conducting rails are separated by distance  $L$  and are on an inclined plane which makes an angle  $\phi$  with the horizontal. There is a uniform vertical magnetic field  $\vec{B} = -B\hat{j}$  everywhere. Gravity is also present. The total resistance of the circuit is a constant value of  $R$ . What is the terminal velocity of the bar? (Terminal velocity is the maximum velocity attained. Another hint: first you must find the induced current using Faraday's Law). Your answer should be in terms of  $m, g, B, R, L$  and  $\phi$ .



$$\mathcal{E}_{ind} = -N \frac{d\Phi_B}{dt} \quad \{N=1\}$$

$$\mathcal{E}_{ind} = -\frac{d}{dt} \int \vec{B} \cdot \hat{n} da$$

$$\mathcal{E}_{ind} = -\frac{d}{dt} \int B da \cos(\pi - \phi)$$

$$\mathcal{E}_{ind} = -\frac{d}{dt} B (-\cos \phi) \int_0^x L dx$$

$$\mathcal{E}_{ind} = BL \frac{dx}{dt} \cos \phi$$

$$\mathcal{E}_{ind} = BLv \cos \phi$$

$$I_{ind} = \frac{\mathcal{E}_{ind}}{R} = \frac{BLv \cos \phi}{R}$$

if  $v \rightarrow v_{Terminal}$   
 $a \rightarrow 0!$

System: bar

$$\vec{F}_{net} = m\vec{a}$$

$$\vec{F}_g + \vec{F}_n + \vec{F}_B = 0$$

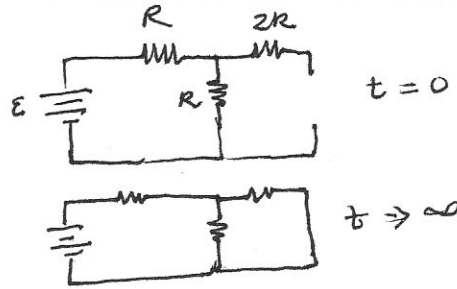
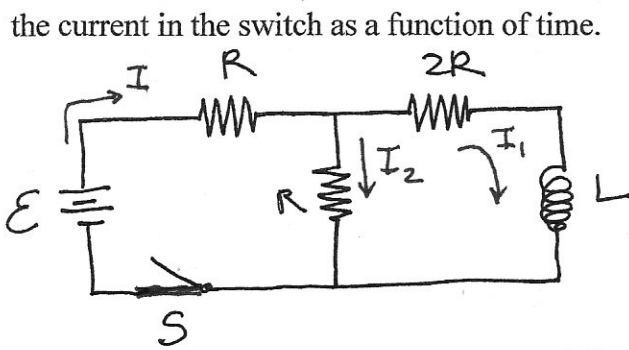
$$\hat{i}: -F_B \cos \phi + F_g \sin \phi = 0$$

$$I_{ind} L B \cos \phi = mg \sin \phi$$

$$\frac{B^2 L^2 \cos^2 \phi v_T}{R} = mg \sin \phi$$

$$v_T = \frac{mgR \sin \phi}{B^2 L^2 \cos^2 \phi}$$

4. In the circuit shown, the switch  $S$  is closed at  $t = 0$ . Find the current in the inductor as a function of time and the current in the switch as a function of time.



$$(1) \quad \mathcal{E} - IR - I_1 2R - L \frac{dI_1}{dt} = 0$$

$$(2) \quad \mathcal{E} - IR - I_2 R = 0$$

$$(3) \quad I = I_1 + I_2$$

$$I_2 = I - I_1 \quad (\text{put in (2)})$$

$$\mathcal{E} - IR - (I - I_1)R = 0$$

$$\mathcal{E} - 2IR + I_1 R = 0$$

$$* \quad 2IR = \mathcal{E} + I_1 R \quad (\text{put in (1)} \times 2)$$

$$(1) \times 2 \quad 2\mathcal{E} - 2IR - 2I_1 2R - 2L \frac{dI_1}{dt} = 0$$

$$2\mathcal{E} - (\mathcal{E} + I_1 R) - 4I_1 R - 2L \frac{dI_1}{dt} = 0$$

$$\mathcal{E} - 5I_1 R - 2L \frac{dI_1}{dt} = 0$$

(Separate variables)  
 $\div$  by  $5R$

$$-\frac{2L}{5R} \frac{dI_1}{dt} = I_1 - \frac{\mathcal{E}}{5R}$$

$$\int_0^{I_1} \frac{dI_1}{(I_1 - \mathcal{E}/5R)} = \int_0^t \frac{-5R}{2L} dt$$

$$\ln \frac{I_1 - \mathcal{E}/5R}{-\mathcal{E}/5R} = \frac{-5R}{2L} t$$

$$I_1 - \mathcal{E}/5R = -\mathcal{E}/5R (e^{-5R/2Lt})$$

$$\boxed{I_1 = \mathcal{E}/5R (1 - e^{-5R/2Lt})}$$

INDUCTOR

use \* to find  $I$  for the current thru  $S$

$$* \quad I = \frac{\mathcal{E}}{2R} + \frac{I_1}{2}$$

$$I = \frac{\mathcal{E}}{2R} + \frac{\mathcal{E}}{10R} - \frac{\mathcal{E}}{10R} e^{-5R/2Lt}$$

$$I = \frac{5\mathcal{E}}{10R} + \frac{1\mathcal{E}}{10R} - \frac{1\mathcal{E}}{10R} e^{-5R/2Lt}$$

$$I = \frac{3\mathcal{E}}{5R} - \frac{1\mathcal{E}}{10R} e^{-5R/2Lt}$$

$$\boxed{I = \frac{\mathcal{E}}{5R} (3 - \frac{1}{2} e^{-5R/2Lt})}$$

SWITCH