

# Mechanics Center of Mass

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#### Last time

- isolated and nonisolated systems
- mechanical energy
- conservation of mechanical energy
- general conservation of energy
- how to solve energy problems

## **Overview**

- go over quiz 4
- another energy example
- center of mass

## Another Energy Example

#### Ch 8, #80

A 1400 kg block of granite is pulled up an incline at a constant speed of 1.34 m/s by a cable and winch. The indicated distances are  $d_1 = 40$  m and  $d_2 = 30$  m. The coefficient of kinetic friction between the block and the incline is 0.40. What is the power due to the force applied to the block by the cable?



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Possible strategies:

- 1. Newton's 2nd law
- 2. Work-KE theorem, system is block only
- 3. Energy conservation with potential energy, system is block, earth, internal degrees of freedom in surfaces

### **Another Energy Example**



Ans:

$$P = 1.7 \times 10^4 \text{ W}$$

For a solid, rigid object:

#### center of mass

the point on an object where we can model all the mass as being, in order to find the object's trajectory; a freely moving object rotates about this point

also, the point at which if all the forces the object are modeled to act, the motion of that point is correctly predicted

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The center of mass of the wrench follows a straight line as the wrench rotates about that point.



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 $^1 \rm Figure~from$  http://www4.uwsp.edu/physastr/kmenning/Phys203/Lect18.html

For a system of two particles, 1 dimension:

$$x_{\rm CM} = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$$



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For more particles in 1 dimension:

$$x_{\rm CM} = \frac{\sum_i m_i x_i}{\sum_i m_i}$$

or

$$x_{\rm CM} = \frac{1}{M} \sum_i m_i x_i$$

where M is the total mass of all the particles in the system.

This expression also gives us the x coordinate of the center of mass when we have more dimensions.

$$x_{\rm CM} = \frac{1}{M} \sum_i m_i x_i$$

Likewise for *y*:

$$y_{\mathsf{CM}} = \frac{1}{M} \sum_{i} m_i y_i$$

and z:

$$z_{\rm CM} = rac{1}{M} \sum_i m_i z_i$$

where M is the total mass of all the particles in the system.

Therefore, we can condense all three expressions into a single vector expression.

$$\mathbf{r}_{\mathsf{CM}} = \frac{1}{M} \sum_{i} m_i \mathbf{r}_i$$

where  $\mathbf{r}_i = x_i \mathbf{i} + y_i \mathbf{j} + z_i \mathbf{k}$  is the displacement of particle *i* from the origin.

## Summary

- went over quiz 4
- another energy example
- center of mass

**Test 2** either Wed Nov 14 or Thurs, Nov 15 - give feedback asap.

### Homework

- finish energy HW questions
- (Ch 9 Ques: 1; Probs: 1, 3, 5 can wait to do)