



# **Mechanics**

## **Rotational Inertia**

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## Last time

- torque
- net torque
- static equilibrium

# Overview

- another static equilibrium example
- Newton's second law for rotation
- moment of inertia
- (parallel axis theorem)

## Question

**Quick Quiz 12.3**<sup>1</sup> A meterstick of uniform density is hung from a string tied at the 25-cm mark. A 0.50-kg object is hung from the zero end of the meterstick, and the meterstick is balanced horizontally. What is the mass of the meterstick?

- (A) 0.25 kg
- (B) 0.50 kg
- (C) 1.0 kg
- (D) 2.0 kg

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<sup>1</sup>Serway & Jewett, page 366.

## Question

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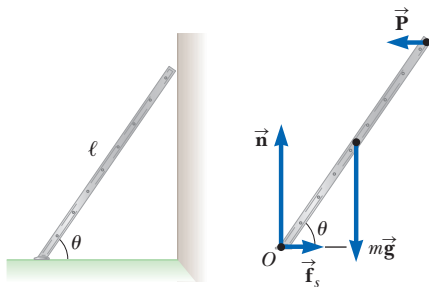
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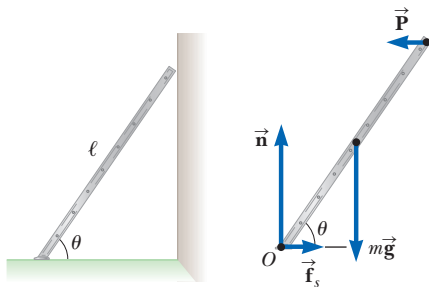
## Example - Slipping Ladder

A uniform ladder of length  $\ell$ , rests against a smooth, vertical wall. The mass of the ladder is  $m$ , and the coefficient of static friction between the ladder and the ground is  $\mu_s = 0.40$ . Find the minimum angle  $\theta_{\min}$  at which the ladder does not slip.



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$$\theta_{\min} = 51^\circ$$

## Rotational Version of Newton's Second Law

Tangential components of forces give rise to torques.

They also cause tangential accelerations. Consider the tangential component of the net force,  $\mathbf{F}_{\text{net},t}$ :

$$\mathbf{F}_{\text{net},t} = m a_t$$

from Newton's second law.

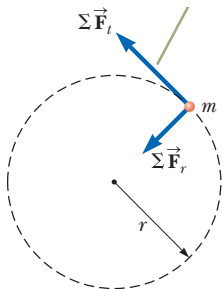
$$\boldsymbol{\tau}_{\text{net}} = \mathbf{r} \times \mathbf{F}_{\text{net}} = r F_{\text{net},t} \hat{\mathbf{n}}$$

Now let's specifically consider the case of a single particle, mass  $m$ , at a fixed radius  $r$ .



# Rotational Version of Newton's Second Law

A single particle, mass  $m$ , at a fixed radius  $r$ .



For such a particle,  $\mathbf{F}_{\text{net},t} = m\mathbf{a}_t$

$$\begin{aligned}\boldsymbol{\tau}_{\text{net}} &= rF_{\text{net},t} \hat{\mathbf{n}} \\ &= r m a_t \hat{\mathbf{n}} \\ &= r m (\alpha r) \\ &= (mr^2) \alpha\end{aligned}$$

## Rotational Version of Newton's Second Law

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Let this constant be (scalar)  $I = mr^2$ .

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Replacing the constant quantity in our expression for  $\tau_{\text{net}}$ :

$$\tau_{\text{net}} = I\alpha$$

# Rotational Version of Newton's Second Law

Compare!

$$\boldsymbol{\tau}_{\text{net}} = I\boldsymbol{\alpha}$$

$$\mathbf{F}_{\text{net}} = m\mathbf{a}$$

Now the moment of inertia,  $I$ , stands in for the inertial mass,  $m$ .

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The moment of inertia measures the rotational inertia of an object, just as mass is a measure of inertia.

## Rotational Inertia, or, Moment of Inertia

We just found that for a single particle, mass  $m$ , radius  $r$ ,

$$I = mr^2$$

However, this will not be the moment of inertia for an extended object with mass distributed over varying distances from the rotational axis.

For that case, the torque on each individual mass  $m_i$  will be:

$$\tau_i = m_i r_i^2 \alpha$$

And we sum over these torques to get the net torque. So, for a collection of particles, masses  $m_i$  at radiuses  $r_i$ :

$$I = \sum_i m_i r_i^2$$

# Moment of Inertia

Important caveat: Moment of inertia depends on the object's mass, shape, and the axis of rotation.

A single object will have different moments of inertia for different axes of rotation.



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A single object will have different moments of inertia for different axes of rotation.

Also notice that this sum is similar to the expression for the center-of-mass, but for  $I$  we have  $r^2$  dependence and we do not divide by the total mass.

Units:  $\text{kg m}^2$

# Moment of Inertia

If the object's mass is far from the point of rotation, more torque is needed to rotate the object (with some angular acceleration).



**Easier Rotation**



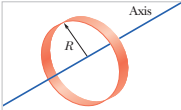
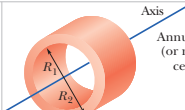
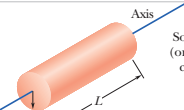
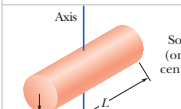
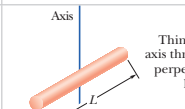
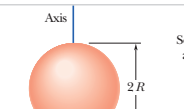
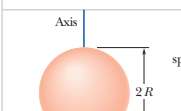
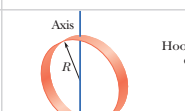
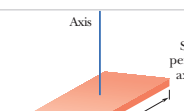
**Difficult Rotation**

The barbell on the right has a greater moment of inertia.

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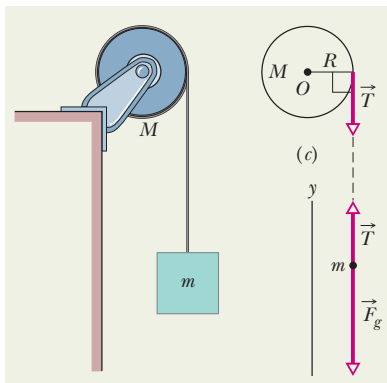
<sup>1</sup>Diagram from Dr. Hunter's page at <http://biomech.byu.edu> (by Hewitt?)

# Moments of Inertia

 <p>Axis</p> <p>Hoop about central axis</p> <p><math>I = MR^2</math></p> <p>(a)</p>	 <p>Axis</p> <p>Annular cylinder (or ring) about central axis</p> <p><math>I = \frac{1}{2}M(R_1^2 + R_2^2)</math></p> <p>(b)</p>	 <p>Axis</p> <p>Solid cylinder (or disk) about central axis</p> <p><math>I = \frac{1}{2}MR^2</math></p> <p>(c)</p>
 <p>Axis</p> <p>Solid cylinder (or disk) about central diameter</p> <p><math>I = \frac{1}{4}MR^2 + \frac{1}{12}ML^2</math></p> <p>(d)</p>	 <p>Axis</p> <p>Thin rod about axis through center perpendicular to length</p> <p><math>I = \frac{1}{12}ML^2</math></p> <p>(e)</p>	 <p>Axis</p> <p>Solid sphere about any diameter</p> <p><math>I = \frac{2}{5}MR^2</math></p> <p>(f)</p>
 <p>Axis</p> <p>Thin spherical shell about any diameter</p> <p><math>I = \frac{2}{3}MR^2</math></p> <p>(g)</p>	 <p>Axis</p> <p>Hoop about any diameter</p> <p><math>I = \frac{1}{2}MR^2</math></p> <p>(h)</p>	 <p>Axis</p> <p>Slab about perpendicular axis through center</p> <p><math>I = \frac{1}{12}M(a^2 + b^2)</math></p> <p>(i)</p>

## Newton's Second Law for Rotation - Example

A block of mass  $m$  is attached to a string wrapped around a pulley wheel of radius  $R$  and mass  $M$ . The block is released from rest and descends. The pulley wheel is a uniform disk, its axle is frictionless, and the string does not slip.



Find the acceleration of the block,  $\mathbf{a}$ , the angular acceleration of the pulley wheel,  $\alpha$ , and the tension in the string,  $T$ .

## Newton's Second Law for Rotation - Example

block:

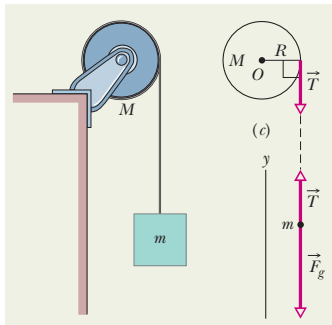
$$\begin{aligned} F_{\text{net},y} &= ma_y \\ T - mg &= -ma \end{aligned} \quad (1)$$

pulley:

$$\begin{aligned} \tau_{\text{net}} &= I\alpha \\ RT &= \frac{1}{2}MR^2\alpha \\ T &= \frac{1}{2}MR\alpha \end{aligned} \quad (2)$$

rotational and translational acceleration:

$$a = R\alpha \quad (3)$$



## Newton's Second Law for Rotation - Example

(3) into (2):

$$T = \frac{1}{2}Ma$$

Putting that into (1) and rearranging:

$$\left(\frac{1}{2}Ma\right) - mg = -ma$$

$$\mathbf{a} = \frac{2mg}{M + 2m} \text{ downward}$$

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Eq for  $a$  into (2):

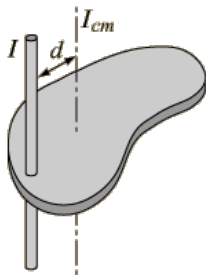
$$T = \frac{Mmg}{M + 2m}$$

Eq for  $a$  into (3):

$$\alpha = \frac{2mg}{R(M + 2m)} \text{ clockwise}$$

## Moment of Inertia - Parallel Axis Theorem

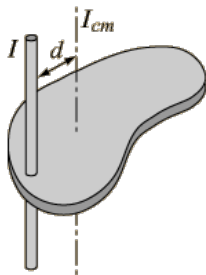
Suppose you need the moment of inertia about an axis not through the center of mass, but all you know is  $I_{CM}$ .





## Moment of Inertia - Parallel Axis Theorem

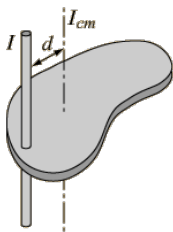
Suppose you need the moment of inertia about an axis not through the center of mass, but all you know is  $I_{CM}$ .



We can determine the moment of inertia about any parallel axis with a simple calculation!

$$I_{\parallel} = I_{CM} + M d^2$$

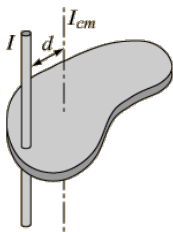
## Moment of Inertia - Parallel Axis Theorem



For an axis through the center of mass and any parallel axis through some other point:

$$I_{\parallel} = I_{CM} + M d^2$$

# Moment of Inertia - Parallel Axis Theorem



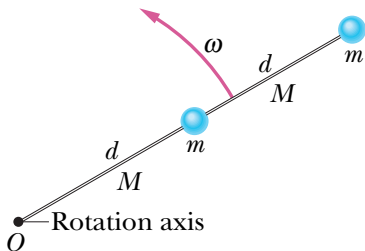
For an axis through the center of mass and any parallel axis through some other point:

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Use: perhaps you know  $I_{CM}$ , but need the moment of inertia about a different point; or maybe you know the moment of inertia about one axis, you can find  $I_{CM}$ , then you can find  $I$  for **any** parallel axis.

## Example based on problem 41, pg 269

Two particles, each with mass  $m = 0.85$  kg, are fastened to each other, and to a rotation axis at  $O$ , by two thin rods, each with length  $d = 5.6$  cm and mass  $M = 1.2$  kg. Measured about  $O$ , what is the combination's rotational inertia?

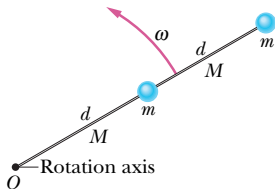


## Example based on problem 41, pg 269

$$m = 0.85 \text{ kg}$$

$$d = 5.6 \text{ cm}$$

$$M = 1.2 \text{ kg}$$



For the two particles  $I = mr^2$ , so in total:

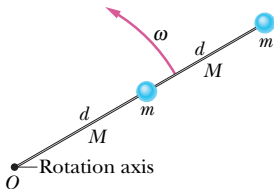
$$I_{\text{particles}} = md^2 + m(2d)^2$$

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For the two particles  $I = mr^2$ , so in total:

$$I_{\text{particles}} = md^2 + m(2d)^2$$

For the rods, treat them as one,  $I_{\text{CM}} = \frac{1}{12}M_{\text{tot}}L^2$ , if  $L = 2d$  is the rod length and  $M_{\text{tot}} = 2M$ .

Using the parallel axis theorem, we can find the rotational inertia through its end point, a distance  $d$  away:

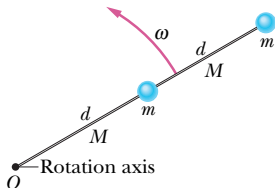
$$I_{\text{rod}} = \frac{1}{12}(2M)(2d)^2 + (2M)d^2$$

## Example based on problem 41, pg 269

$$m = 0.85 \text{ kg}$$

$$d = 5.6 \text{ cm}$$

$$M = 1.2 \text{ kg}$$



In total:

$$\begin{aligned} I_O &= md^2 + m(2d)^2 + \frac{1}{12}(2M)(2d)^2 + (2M)d^2 \\ &= 5md^2 + \frac{8}{3}Md^2 \\ &= \underline{2.3 \times 10^{-2} \text{ kg m}^2} \end{aligned}$$

# Summary

- static equilibrium example
- Newton's second law for rotation
- moment of inertia
- (parallel axis theorem)

## Homework

- Ch 10 Probs: 49, 53 - Newton's 2nd law for rotation
- Ch 10 Probs: 37, 43, 104(a) only [not (b)] (can wait to do)