



# Mechanics

## Vectors

Lana Sheridan

De Anza College

Oct 4, 2018

## Last time

- free fall

# Overview

- representing vectors
- vector properties

# Math you will need for 2-Dimensions

Before going into motion in 2 dimensions, we will review some things about vectors.

# Vectors

## scalar

A scalar quantity indicates an amount. It is represented by a real number. (Assuming it is a physical quantity.)

## vector

A vector quantity indicates both an amount and a direction. It is represented more than one real number. (Assuming it is a physical quantity.)

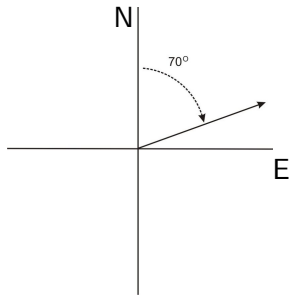
There are many ways to represent a vector.

- a magnitude and (an) angle(s)
- magnitudes in several perpendicular directions

# Representing Vectors: Angles

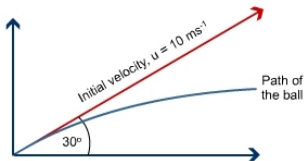
## Bearing angles

Example, a plane flies  $750 \text{ km h}^{-1}$   
at a bearing of  $70^\circ$



## Generic reference angles

A baseball is thrown at  $10 \text{ m s}^{-1}$ ,  $30^\circ$  above the horizontal.



# Representing Vectors: Unit Vectors

Magnitudes in several perpendicular directions: using *unit vectors*.

Unit vectors have a magnitude of one unit.

# Representing Vectors: Unit Vectors

Magnitudes in several perpendicular directions: using *unit vectors*.

Unit vectors have a magnitude of one unit.

A set of perpendicular unit vectors defines a *basis* or decomposition of a vector space.



# Representing Vectors: Unit Vectors

Magnitudes in several perpendicular directions: using *unit vectors*.

Unit vectors have a magnitude of one unit.

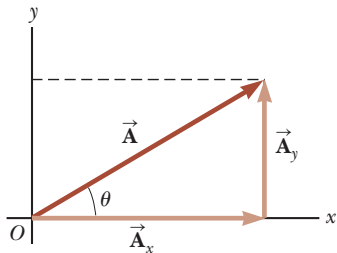
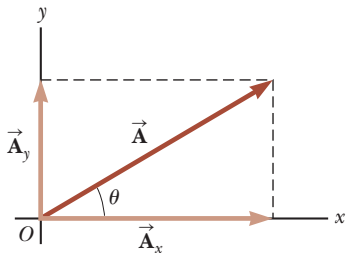
A set of perpendicular unit vectors defines a *basis* or decomposition of a vector space.

In two dimensions, a pair of perpendicular unit vectors are usually denoted  $\mathbf{i}$  and  $\mathbf{j}$  (or sometimes  $\hat{\mathbf{x}}, \hat{\mathbf{y}}$ ).

# Components

Consider the 2 dimensional vector  $\mathbf{A} = A_x\mathbf{i} + A_y\mathbf{j}$ , where  $A_x$  and  $A_y$  are numbers.

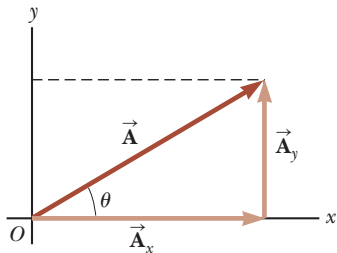
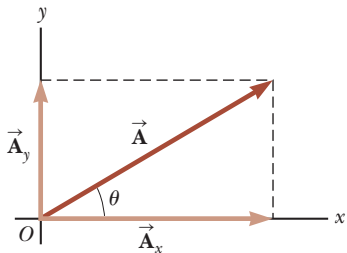
We then say that  $A_x$  is the  $i$ -component (or  $x$ -component) of  $\mathbf{A}$  and  $A_y$  is the  $j$ -component (or  $y$ -component) of  $\mathbf{A}$ .



Notice that  $A_x = A \cos \theta$  and  $A_y = A \sin \theta$ .

# Components vs Magnitude-and-Angle Notation

Notice that  $A_x = A \cos \theta$  and  $A_y = A \sin \theta$ .



Also notice,

$$A = |\mathbf{A}| = \sqrt{A_x^2 + A_y^2}$$

and

$$\theta = \tan^{-1} \left( \frac{A_y}{A_x} \right)$$

**if** the angle is given as shown.

# Why Vectors?

Of course, there is no reason to limit this to two dimensions.

## Why Vectors?

Of course, there is no reason to limit this to two dimensions.

With three dimensions we introduce another unit vector  $\mathbf{k} = \hat{\mathbf{z}}$ .  
And we can have as many dimensions as we need by adding more perpendicular unit vectors.

## Why Vectors?

Of course, there is no reason to limit this to two dimensions.

With three dimensions we introduce another unit vector  $\mathbf{k} = \hat{\mathbf{z}}$ .  
And we can have as many dimensions as we need by adding more perpendicular unit vectors.

Vectors are the right tool for working in higher dimensions.

# Why Vectors?

Of course, there is no reason to limit this to two dimensions.

With three dimensions we introduce another unit vector  $\mathbf{k} = \hat{\mathbf{z}}$ .  
And we can have as many dimensions as we need by adding more perpendicular unit vectors.

Vectors are the right tool for working in higher dimensions.

They have a property that correctly reflects what it means for there to be more than one dimension: that **each perpendicular direction is independent of the others.**

# Why Vectors?

Of course, there is no reason to limit this to two dimensions.

With three dimensions we introduce another unit vector  $\mathbf{k} = \hat{\mathbf{z}}$ .  
And we can have as many dimensions as we need by adding more perpendicular unit vectors.

Vectors are the right tool for working in higher dimensions.

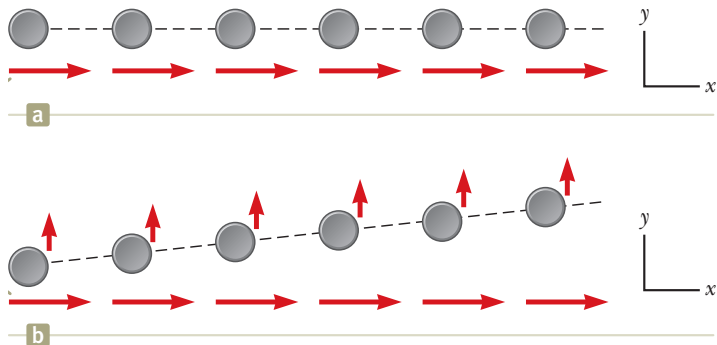
They have a property that correctly reflects what it means for there to be more than one dimension: that **each perpendicular direction is independent of the others.**

This makes life much easier: we will be able to solve for motion in the  $x$  direction separately from motion in the  $y$  direction.



## Visualizing Motion in 2 Dimensions

Imagine an air hockey puck moving with horizontally constant velocity:



If it experiences a momentary upward (in the diagram) acceleration, it will have a component of velocity upwards.

**The horizontal motion remains unchanged!**

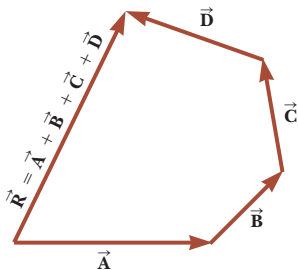
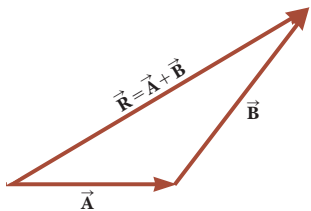
# Vectors Properties and Operations

## Equality

Vectors  $\mathbf{A} = \mathbf{B}$  if and only if the magnitudes and directions are the same. (Each component is the same.)

## Addition

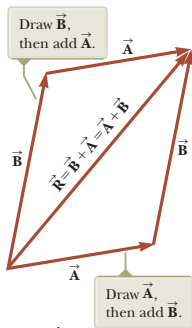
$\mathbf{A} + \mathbf{B}$



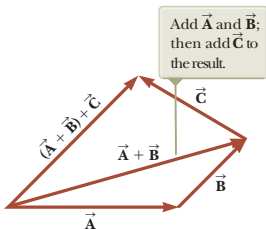
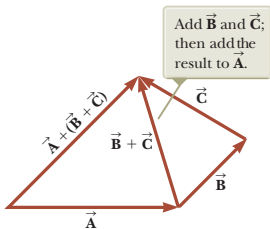
# Vectors Properties and Operations

## Properties of Addition

- $\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$  (commutative)



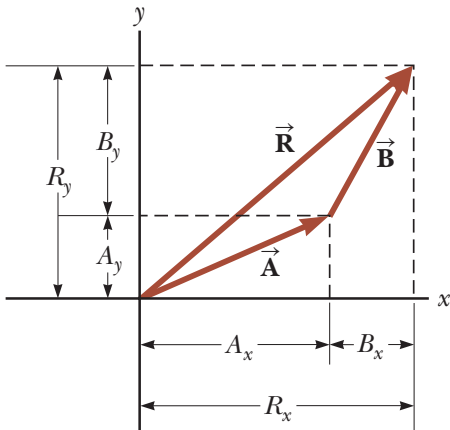
- $(\mathbf{A} + \mathbf{B}) + \mathbf{C} = \mathbf{A} + (\mathbf{B} + \mathbf{C})$  (associative)



# Vectors Properties and Operations

Doing addition:

Almost always the right answer is to break each vector into components and sum each component independently.



# Vectors Properties and Operations

Doing addition:

Almost always the right answer is to break each vector into components and sum each component independently.

## Example

$\mathbf{w} = 5 \text{ m}$  at  $36.9^\circ$  above the horizontal.

$\mathbf{u} = 17 \text{ m}$  at  $28.1^\circ$  above the horizontal.

# Vectors Properties and Operations

Doing addition:

Almost always the right answer is to break each vector into components and sum each component independently.

## Example

$\mathbf{w} = 5 \text{ m}$  at  $36.9^\circ$  above the horizontal.

$\mathbf{u} = 17 \text{ m}$  at  $28.1^\circ$  above the horizontal.

This means  $\mathbf{w} = 4\mathbf{i} + 3\mathbf{j} \text{ m}$  and  $\mathbf{u} = 15\mathbf{i} + 8\mathbf{j} \text{ m}$ .

$$\mathbf{w} + \mathbf{u} = ?$$

# Vectors Properties and Operations

Doing addition:

Almost always the right answer is to break each vector into components and sum each component independently.

## Example

$\mathbf{w} = 5 \text{ m}$  at  $36.9^\circ$  above the horizontal.

$\mathbf{u} = 17 \text{ m}$  at  $28.1^\circ$  above the horizontal.

This means  $\mathbf{w} = 4\mathbf{i} + 3\mathbf{j} \text{ m}$  and  $\mathbf{u} = 15\mathbf{i} + 8\mathbf{j} \text{ m}$ .

$$\begin{aligned}\mathbf{w} + \mathbf{u} &= ? \\ &= (4 + 15)\mathbf{i} + (3 + 8)\mathbf{j} \\ &= (19\mathbf{i} + 11\mathbf{j}) \text{ m}\end{aligned}$$

or  $22.0 \text{ m}$  at  $30.1^\circ$  above the horizontal.

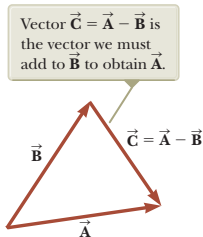
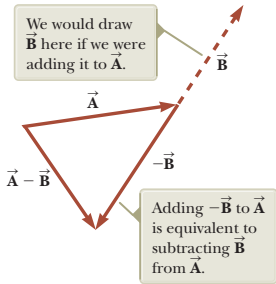
# Vectors Properties and Operations

## Negation

If  $\mathbf{u} = -\mathbf{v}$  then  $\mathbf{u}$  has the same magnitude as  $\mathbf{v}$  but points in the **opposite** direction.

## Subtraction

$$\mathbf{A} - \mathbf{B} = \mathbf{A} + (-\mathbf{B})$$





# Summary

- vectors

## Homework

- announced yesterday: Ch 3 Questions: 1, 4, 7; Problems: 1, 3, 5.
- new: Ch 3 Problems: 11, 15.
- new: Ch 4 Problem 76, 83 (relative motion - can wait to do).