

# Rotation Nonisolated Systems & Angular Momentum Oscillations Simple Harmonic Motion

Lana Sheridan

De Anza College

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#### Last Time

- angular momentum of an object moving in a straight line
- conservation of angular momentum

#### **Overview**

• torque and changes in angular momentum



A massive flywheel is driven to cause rotations in the entire rocket.

## #42, page 359

42. A spacecraft is in empty space. It carries on board a gyroscope with a moment of inertia of  $I_g = 20.0 \text{ kg} \cdot \text{m}^2$  about the axis of the gyroscope. The moment of inertia of the spacecraft around the same axis is  $I_s = 5.00 \times 10^5 \text{ kg} \cdot \text{m}^2$ . Neither the spacecraft nor the gyroscope is originally rotating. The gyroscope can be powered up in a negligible period of time to an angular speed of 100 rad/s. If the orientation of the spacecraft is to be changed by 30.0°, for what time interval should the gyroscope be operated?

Time of gyroscope operation to achieve  $30.0^{\circ}$  rotation of craft?

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t = 131 s

### **Conservation of Angular Momentum**

For an *isolated* system, *ie.* a system with no external torques, total angular momentum is *conserved*.



<sup>1</sup>Figures from Serway & Jewett.

#### **Non-isolated System**



$$\vec{\tau}_{ext} = \frac{d\vec{L}}{dt}$$

#### **Recap of Non-isolated Systems**



#### Non-isolated Example

A sphere of mass  $m_1$  and a block of mass  $m_2$  are connected by a light cord that passes over a pulley as shown. The radius of the pulley is R, and the mass of the thin rim is M. The spokes of the pulley have negligible mass. The block slides on a frictionless, horizontal surface. Find an expression for the linear acceleration of the two objects.



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# Non-isolated Example (11.4)

The system: block, sphere, and pulley.



Consider the angular momentum and torques about the axis of the pulley.

The only net external torque on this system is from the force of gravity on  $m_1$ .

### Non-isolated Example (11.4)

$$\vec{\tau}_{net,ext} = \frac{d\vec{L}}{dt}$$

$$m_1gR = \frac{d}{dt}(m_1vR + m_2vR + I\omega)$$

$$m_1gR = \frac{d}{dt}(m_1vR + m_2vR + (MR^2)\frac{v}{R})$$

$$m_1gR = \frac{dv}{dt}(m_1 + m_2 + M)R$$

$$a = \frac{m_1g}{(m_1 + m_2 + M)}$$



Tops, gyroscopes, and other spinning objects with a fixed point on their axis of rotation exhibit interesting behavior.



Tops, gyroscopes, and other spinning objects with a fixed point on their axis of rotation exhibit interesting behavior.

In particular, they are stable against an external gravitational force.

The effect of gravity is to cause *precession*.

Precessional motion is an additional rotation of the object's rotation axis. A smooth change in the angular momentum!

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$$\vec{\tau}_{ext} = \frac{d\vec{L}}{dt}$$

The change in angular momentum must be in the direction of the external torque!



The torque supplied by the gravitational force is perpendicular to the force itself.

The magnitude of the angular momentum doesn't change - only the direction.

We can find the value for the precession angular speed  $\omega_p$  if we make an approximation.

Suppose that the top spins with angular speed  $\omega$ , and let  $\omega$  be very large. Then the top's angular momentum  $L = I\omega$  without considering the precessional motion is almost the same as its total angular momentum *with* the precession:

$$\vec{L} \approx \vec{L}_{tot}$$

This is a reasonable approximation as long as  $\omega >> \omega_p$ .





Angular speed of precession:

$$\omega_p = \frac{d\phi}{dt}$$



#### Summary

• conservation of angular momentum

4th Assignment due Friday, Mar 20.

**Final Exam** Tuesday, Mar 24, via Canvas & Zoom, be ready at 9am.

## (Uncollected) Homework

• Play with tops, bicycle wheels, gyroscopes, etc., whatever you have in your house

Serway & Jewett:

- Ch 11, onward from page 357. Problems: 30, 51, 45, 53, 55
- Look at example 11.9.