

# Physics 4B Winter 2018 Sample Equation Sheet

March, 2018

Please show your work! Answer as many questions as you can, in any order. Calculators are allowed. Books, notes, and internet connectable devices are not allowed. Use any blank space to answer questions, but please make sure it is clear which question your answer refers to. When asked for an expression, give your answer only in terms of the variables given in the question and fundamental constants such as  $g$ ,  $k$ ,  $e$ , and so on.

**DO NOT OPEN TEST BOOKLET UNTIL TOLD TO DO SO.**

## Maxwell's Equations

$$\oint \mathbf{E} \cdot d\mathbf{A} = \frac{q_{\text{enc}}}{\epsilon_0} \quad \oint \mathbf{B} \cdot d\mathbf{A} = 0$$
$$\oint \mathbf{E} \cdot d\mathbf{s} = -\frac{d\Phi_B}{dt} \quad \oint \mathbf{B} \cdot d\mathbf{s} = \mu_0 I_{\text{enc}} + \mu_0 \epsilon_0 \frac{d\Phi_E}{dt}$$

## Constants

$$k = \frac{1}{4\pi\epsilon_0} = 8.99 \times 10^9 \text{ Nm}^2\text{C}^{-2} \quad \epsilon_0 = 8.854 \times 10^{-12} \text{ C}^2\text{N}^{-1}\text{m}^{-2} \quad \mu_0 = 4\pi \times 10^{-7} \text{ H/m}$$
$$g = 9.807 \text{ m s}^{-2} \quad e = 1.602 \times 10^{-19} \text{ C} \quad c = \frac{1}{\sqrt{\mu_0\epsilon_0}} = 2.998 \times 10^8 \text{ m/s}$$
$$m_e = 9.109 \times 10^{-31} \text{ kg} \quad m_p = 1.673 \times 10^{-27} \text{ kg} \quad m_n = 1.675 \times 10^{-27} \text{ kg}$$

## Trigonometric Identities

$$\sin^2 \theta + \cos^2 \theta = 1 \quad \cos \alpha \cos \beta = \frac{1}{2}[\cos(\alpha - \beta) + \cos(\alpha + \beta)]$$
$$\sin(2\theta) = 2 \sin(\theta) \cos(\theta) \quad \sin \alpha \sin \beta = \frac{1}{2}[\cos(\alpha - \beta) - \cos(\alpha + \beta)]$$
$$\cos(2\theta) = \cos^2 \theta - \sin^2 \theta \quad \sin \alpha \cos \beta = \frac{1}{2}[\sin(\alpha + \beta) + \sin(\alpha - \beta)]$$
$$\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta \quad \sin\left(\theta + \frac{\pi}{2}\right) = \cos \theta$$
$$\cos(\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta \quad \cos\left(\theta + \frac{\pi}{2}\right) = -\sin \theta$$
$$\sec \theta := \frac{1}{\cos \theta}$$
$$\csc \theta := \frac{1}{\sin \theta}$$
$$\cot \theta := \frac{1}{\tan \theta}$$

$$\begin{aligned}
\mathbf{F} &= q\mathbf{E} + q\mathbf{v} \times \mathbf{B} & \mathbf{F} &= \frac{kq_1q_2}{r^2} \hat{\mathbf{r}} \\
E &= \frac{\sigma}{2\epsilon_0} & E &= \frac{\sigma}{\epsilon_0} & E &= 2\pi k\sigma \left(1 - \frac{x}{\sqrt{R^2+x^2}}\right) \\
\Phi_E &= \int \mathbf{E} \cdot d\mathbf{A} & \Phi_B &= \int \mathbf{B} \cdot d\mathbf{A} \\
U &= qV & U &= \frac{kq_1q_2}{r} & \Delta V &= -\int \mathbf{E} \cdot ds \\
\mathbf{p} &= q\mathbf{d} & \boldsymbol{\tau} &= \mathbf{p} \times \mathbf{E} & U &= -\mathbf{p} \cdot \mathbf{E} \\
\boldsymbol{\mu} &= NIA & \boldsymbol{\tau} &= \boldsymbol{\mu} \times \mathbf{B} & U &= -\boldsymbol{\mu} \cdot \mathbf{B} \\
\mathbf{E} &= \frac{1}{2\pi\epsilon_0} \frac{\mathbf{p}}{z^3} & \mathbf{B} &= \frac{\mu_0}{2\pi} \frac{\boldsymbol{\mu}}{z^3} \\
E &= \frac{kqz}{(R^2+z^2)^{3/2}} & B &= \frac{\mu_0 I R^2}{2(R^2+z^2)^{3/2}} \\
\mathbf{F} &= I \mathbf{L} \times \mathbf{B} & \frac{F_B}{L} &= \frac{\mu_0 I_1 I_2}{2\pi d} \\
\mathbf{B} &= \frac{\mu_0}{4\pi} \frac{q\mathbf{v} \times \hat{\mathbf{r}}}{r^2} & d\mathbf{B} &= \frac{\mu_0}{4\pi} \frac{I ds \times \hat{\mathbf{r}}}{r^2} & \mathbf{B} &= \frac{\mu_0 I}{4\pi a} (\sin \theta_1 - \sin \theta_2) \\
B &= \frac{\mu_0 I}{2\pi r} & B &= \frac{\mu_0 I r}{2\pi R^2} & B &= \mu_0 In \\
r &= \frac{mv_\perp}{|q|B} & T &= \frac{2\pi m}{|q|B} & p &= v_\parallel T \\
C &= \frac{Q}{\Delta V} & C &= \frac{\kappa \epsilon_0 A}{d} \\
C &= 2\pi\epsilon_0 \frac{L}{\ln(b/a)} & C &= 4\pi\epsilon_0 \frac{ab}{b-a} \\
L &= \frac{N\Phi_B}{i} & L &= \mu_0 n^2 A \ell & \mathcal{E}_L &= -L \frac{di}{dt} \\
M &= \frac{N_1 \Phi_{B,2 \rightarrow 1}}{i_2} = \frac{N_2 \Phi_{B,1 \rightarrow 2}}{i_1} & \mathcal{E}_{M,1} &= -M \frac{di_2}{dt} & \Delta V_s &= \Delta V_p \frac{N_s}{N_p} \\
U &= \frac{1}{2} \frac{Q^2}{C} & u &= \frac{1}{2} \epsilon_0 E^2 \\
U_B &= \frac{1}{2} Li^2 & u_B &= \frac{B^2}{2\mu_0} \\
\mathcal{E} &= \frac{dW}{dq} & P &= \frac{dW}{dt} & P &= I \Delta V \\
R &= \frac{\Delta V}{I} & J &= \frac{I}{A} & \rho &= \frac{E}{J} = \frac{1}{\sigma} \\
R &= \frac{\rho L}{A} & \rho - \rho_0 &= \rho_0 \alpha(T - T_0) \\
v_d &= \frac{J}{ne} & \Delta V_H &= \frac{BI}{ent} \\
q(t) &= C\mathcal{E}(1 - e^{-t/\tau_C}) & i(t) &= \frac{\mathcal{E}}{R} e^{-t/\tau_C} & \Delta v_C(t) &= \mathcal{E}(1 - e^{-t/\tau_C}) \\
q(t) &= Q_0 e^{-t/\tau_C} & i(t) &= I_0 e^{-t/\tau_C} & \Delta v_C(t) &= (\Delta V_0) e^{-t/\tau_C} \\
\tau_C &= RC & i(t) &= \frac{\mathcal{E}}{R} (1 - e^{-t/\tau_L}) & \Delta v_L(t) &= \mathcal{E} e^{-t/\tau_L} \\
\tau_L &= \frac{L}{R} & i(t) &= I_0 e^{-t/\tau_L} & \Delta v_L(t) &= (\Delta V_0) e^{-t/\tau_L} \\
X_L &= \omega L & X_C &= \frac{1}{\omega C} & \omega_0 &= \frac{1}{\sqrt{LC}} \\
Z &= \sqrt{R^2 + (X_L - X_C)^2} & \phi &= \tan^{-1} \left( \frac{X_L - X_C}{R} \right) & P_{\text{avg}} &= I_{\text{rms}} \Delta V_{\text{rms}} \cos \phi \\
I_d &= \epsilon_0 \frac{d\Phi_E}{dt} & c &= f\lambda & c &= \frac{E}{B} \\
\mathbf{S} &= \frac{1}{\mu_0} \mathbf{E} \times \mathbf{B} & P_{\text{rad}} &= \frac{S}{c} & P_{\text{rad}} &= \frac{2S}{c}
\end{aligned}$$