

# Fluids, Thermodynamics, Waves, & Optics Optics Lab 8 Lenses

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# **Overview**

- Purpose
- Theory
- Part 3.1: behavior of a converging lens
- Part 3.2: the lens equation
- Part 3.3: thick converging lens

To explore the use of lenses to form images.

You will use the Geometric Optics and Bending Light PhET simulations to explore the how light is manipulated by a lens to form images, both with a thin lens and with a thick lens.

## **Images Formed by Refraction**

In the previous lab, we used this expression,

$$\frac{n_1}{p} + \frac{n_2}{q} = \frac{n_2 - n_1}{R}$$

which relates the object and image distances to the radius of curvature of a refracting surface.

#### Focal Length of a Lens

Lenses are optical devices that can be used to create images.

#### focal length

The focal length of a lens is the distance from a thin lens to where an image is formed when the object is at infinity. For converging lenses, this the the distance to where the incoming parallel rays are focused.



## **Images Formed by Thin Lenses**

We will derive the thin lens equation

$$\frac{1}{f} = \frac{1}{p} + \frac{1}{q}$$

#### And the lens maker's equation

$$\frac{1}{f} = (n-1)\left(\frac{1}{R_1} - \frac{1}{R_2}\right)$$

We do this by considering each side of the lens as a refracting surface.

# **Images Formed by Thin Lenses**

A thick lens:



We can imagine that there first surface forms an image  $I_1$ , and that image becomes the *object* for the second surface.

The pink arrow shows  $I_1$ 

### First image formed

Let 
$$n_1 = 1$$
,  $n_2 = n$ .



## Second image formed

$$\frac{n}{p_2} + \frac{1}{q_2} = \frac{1-n}{R_2}$$

We must relate  $p_2$  to  $q_1$ . The new object is the image from the previous surface so:

$$p_2 = -q_1 + t$$

where t is the lens thickness.

## *p*<sub>2</sub> could be positive (real object)...

If  $q_1$  is negative (virtual image 1)...



 $\dots p_2$  is positive (object in front of surface).

## *p*<sub>2</sub> could be negative (virtual object)...

If  $q_1$  is positive (real image 1)...



...  $p_2$  is negative (object behind surface).

## p<sub>2</sub> could be negative (virtual object)...

If  $q_1$  is positive (real image 1)...



...  $p_2$  is negative (object behind surface). Either way, the sign is taken care of in the expression  $p_2 = -q_1 + t$ .

## Relate the original object to the final image

surface 1 
$$\frac{1}{p_1} + \frac{n}{q_1} = \frac{n-1}{R_1}$$
 (1)  
surface 2  $\frac{n}{(-q_1+t)} + \frac{1}{q_2} = \frac{1-n}{R_2}$ 

For a thick lens, you need to use these two equations!

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surface 2  $\frac{n}{(-q_1+t)} + \frac{1}{q_2} = \frac{1-n}{R_2}$ 

For a thick lens, you need to use these two equations!

For a thin lens, t is negligible, so take it to be zero.

surface 2 
$$-\frac{n}{q_1} + \frac{1}{q_2} = \frac{1-n}{R_2}$$

(2)

Add equation (1) to equation (2) to get

$$\frac{1}{p_1} + \frac{1}{q_2} = (n-1)\left(\frac{1}{R_1} - \frac{1}{R_2}\right)$$

### **Thin Lens Equation**

Lastly, measure the object distance to be  $p = p_1 + t/2$  and  $q = q_2 + t/2$ .

Since *t* is effectively zero, we have:

$$\frac{1}{p} + \frac{1}{q} = (n-1)\left(\frac{1}{R_1} - \frac{1}{R_2}\right)$$

*p* and *q* can vary, but since *n*,  $R_1$ , and  $R_2$  are constant for a fixed lens, we know  $\frac{1}{p} + \frac{1}{q} = \text{const.}$ 

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If  $p \to \infty$ ,  $q \to f$ , by the definition of the focal length.

This gives the thin lens equation

$$\frac{1}{p} + \frac{1}{q} = \frac{1}{f}$$

## Lens Maker's Equation

Thin lens equation

$$\frac{1}{p} + \frac{1}{q} = \frac{1}{f}$$

 $\mathsf{and}$ 

$$\frac{1}{p} + \frac{1}{q} = (n-1)\left(\frac{1}{R_1} - \frac{1}{R_2}\right)$$

The LHS is the inverse of the focal length, giving the lens maker's equation:

$$\frac{1}{f} = (n-1)\left(\frac{1}{R_1} - \frac{1}{R_2}\right)$$

## Magnification with a Lens

By definition,

$$M = \frac{h'}{h}$$

And it follows from simple trigonometry that

$$M = -\frac{q}{p}$$

# Sign Conventions for Lenses!

$rac{1}{p}+rac{1}{q}=rac{1}{f}$				
Variable	is Positive	is Negative		
р	object in front of surface	[virtual object] <sup>1</sup>		
q	image behind lens (real)	image in front of lens (virtual)		
h' (and $M$ )	image upright	image inverted		
$R_1$ and $R_2$	object faces convex surf. (C behind surface)	object faces concave surf. ( <i>C</i> in front of surface)		
f	lens is converging	lens is diverging		

<sup>1</sup>Useful in derivations.

#### **Understanding the Sign of** *f*

$$\frac{1}{f} = (n-1)\left(\frac{1}{R_1} - \frac{1}{R_2}\right)$$

Always  $n \ge 1$ , so (n-1) is positive (if zero, there's no lens!).

 $\left(\frac{1}{R_1}-\frac{1}{R_2}\right)$  could be positive or negative, depending on the signs and magnitudes of  $R_1$  and  $R_2$ .

## Sign Examples: Converging Lenses



# Sign Examples: Diverging Lenses



 $\begin{array}{cccc} R_1 - \mathrm{ve} & R_1 + \mathrm{ve} & R_1 \infty \\ R_2 + \mathrm{ve} & R_2 + \mathrm{ve} & R_2 + \mathrm{ve} \\ & & R_1 > R_2 \\ f - \mathrm{ve} & f - \mathrm{ve} & f - \mathrm{ve} \end{array}$ 

## Geometric Optics: Parts 3.1-3.2



## Lab Activity - Part 3.2

You will plot a graph based on data taken for your object and image distances. From the instruction sheet:

"Measure the object distance p and, without moving the object, measure the image distance q. For a virtual image, record q as negative. Record these points in a table and their inverses. Repeat so that you have 8 pairs of values for p and q. Plot a graph of two of the columns in your table, one on the horizontal axis and one on the vertical, so that the result is a **straight line**. From the graph, extract a value for the focal length. Make sure to include your graph in your submission."

<i>p</i> (cm)	<i>q</i> (cm)	$\frac{1}{p}$ (cm <sup>-1</sup> )	$rac{1}{q} (cm^{-1})$

#### Lab Activity - Part 3.2

- Make sure to label your axes.
- Put a best-fit line through your data points and show the equation of the line on your graph.
- From the best-fit line, find f.

## Bending Light, Prisms: Part 3.3



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