



**Introduction to Mechanics**  
**Dynamics**  
**Forces**  
**Newton's Laws**

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Feb 25, 2020

## Last time

- another example
- relative motion and projectiles

# Overview

- forces
- net force
- equilibrium
- free body diagrams
- Newton's first law
- inertia

# Forces

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We did not consider what the causes of this motion might be. We now will think about that.

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**Forces are a “push” or “pull” that an object experiences because of an interaction.**

Forces are **vectors**.

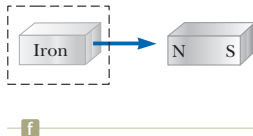
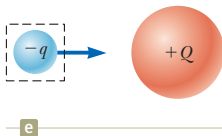
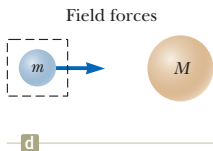
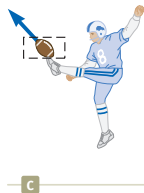
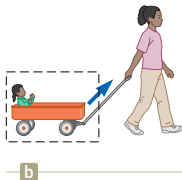
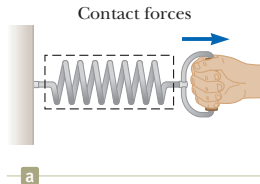
# Forces

## Two types of forces

- **contact forces**  
another object came into contact with the object
- **field forces**  
a kind of interaction between objects without them touching each other

# Forces

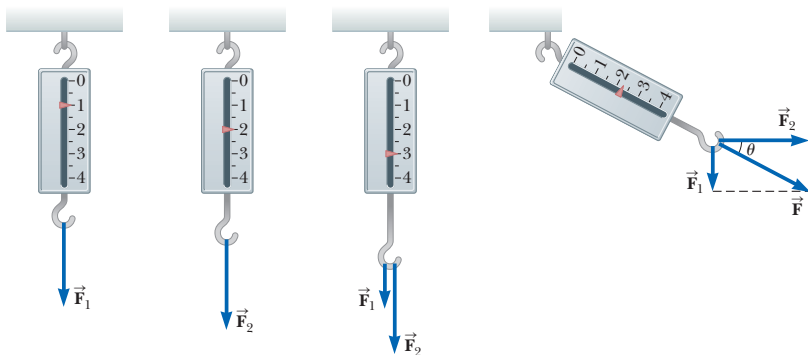
Force type examples:





# Forces are Vectors

We typically draw forces as vector arrows like this:

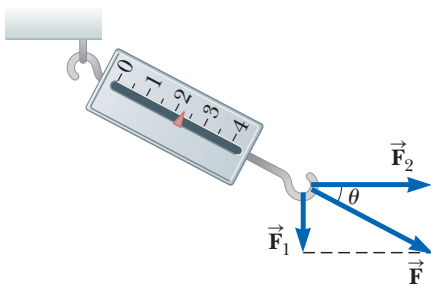


# Net Force

## Net Force

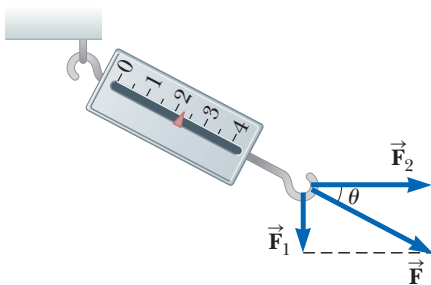
the vector sum of all forces acting on an object.

$$\vec{F}_{\text{net}} = \sum_i \vec{F}_i$$



In the diagram  $\vec{F} = \vec{F}_1 + \vec{F}_2$ .

# Net Force



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The magnitude of  $\vec{F}$  is

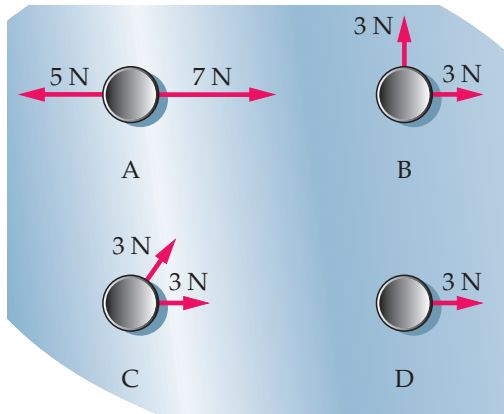
$$F = \sqrt{F_1^2 + F_2^2} = \sqrt{1^2 + 2^2} = 2.23 \text{ N}$$

The direction of  $\vec{F}$  is

$$\theta = \tan^{-1}(F_1/F_2) = 26.6^\circ$$

## Net Force Question

A hockey puck is acted on by one or more forces, as shown. What is the net force on each puck?



In case C, assume that the forces make an angle of  $60^\circ$  to each other.

# Net Force

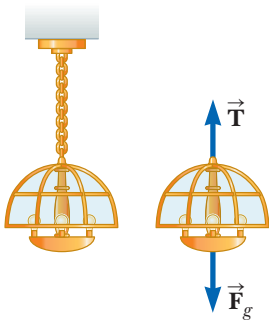
## Net Force

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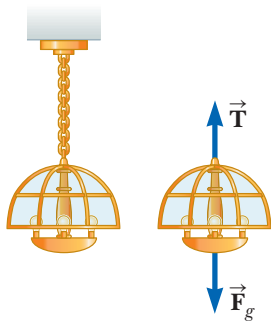
# Net Force and Equilibrium

What is the net force on this lamp?



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When the net force on an object is zero, we say that the object is in **equilibrium**.

## Equilibrium

$$\vec{F}_{\text{net}} = \sum_i \vec{F}_i = 0$$

# Diagrams of Forces

We can draw pictures to aid our reasoning. This is always a good idea.

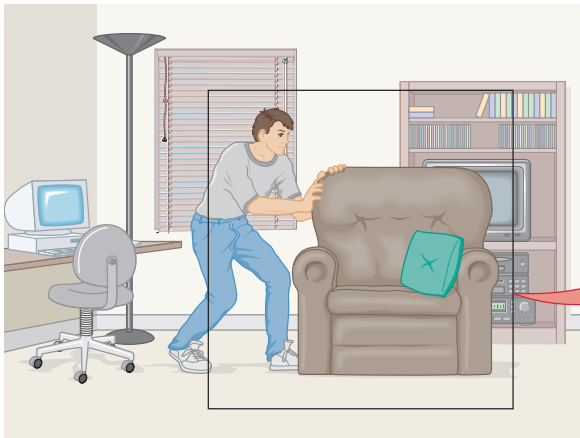
The process will be to identify a **system** of interest. Something we want to study. We will make a mathematical model of it.

Everything that is not part of the system, but interacts with it, is part of the **environment**. We do not describe the environment mathematically.



# Diagrams of Forces

This is a physical picture.



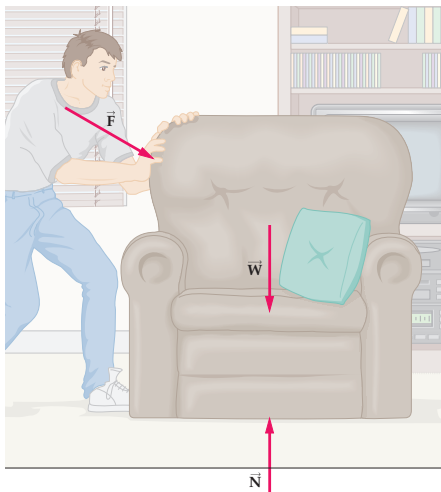
We need to identify the system we want to study. Here: the chair.

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<sup>1</sup>Diagrams from Walker, "Physics".

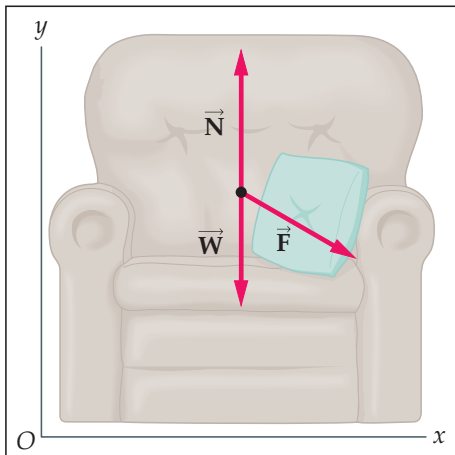
## Diagrams of Forces

This is a physical picture, but now we consider the forces that act on the system (chair) from the environment (everything else).



## Diagrams of Forces: Free-Body Diagram

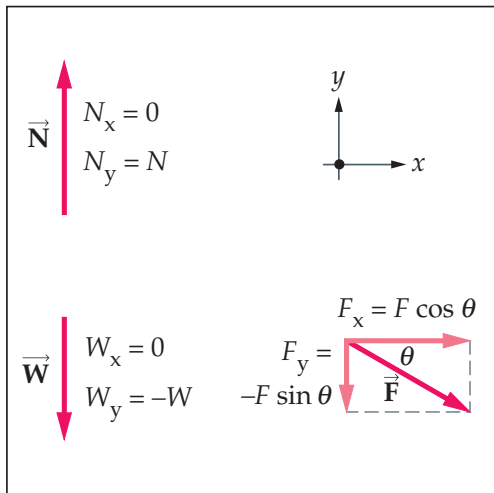
This is a free-body diagram. We represent the chair as a point-particle with force vectors pointing outward.



We also picked a coordinate system ( $x, y$  axes).

# Diagrams of Forces: Free-Body Diagram

To analyze the forces, we must break them into components along our chosen axes.



# Newton

Isaac Newton was able to articulate simple rules that govern the way in which forces act and effect motion.



# Newton's First Law

## Newton I (as commonly stated)

An object in motion will stay in motion with constant velocity and an object at rest will stay at rest, unless acted upon by a (non-zero) net force.

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If an object is in motion and there is zero net force on the object, does its speed have to be constant?

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# Velocity and Newton's First Law

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Yes. What else?

The direction of motion.

Neither the speed or the direction of motion can change. The *velocity* is constant.

## Galileo and Inertia

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As we said earlier, Galileo had already proposed the idea of inertia when he considered balls rolling on inclined surfaces.

**Inertia** (from the Latin word for *lazy*) is the tendency of objects to stay doing whatever they are already doing, unless they are interfered with.

Galileo's idea of inertia:

A body moving on a level surface will continue in the same direction at a constant speed unless disturbed.

Newton specifically understood the “disturbance” to be a net force.

## Newton's First Law / Law of Inertia

This does not really correspond with our expectation from daily life. In our everyday environment, everything seems to naturally slow to a stop.

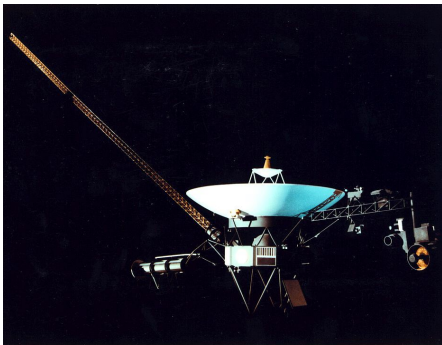
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But we now know of other environments where there are very few resistive forces and we see this behavior.



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# Newton's First Law

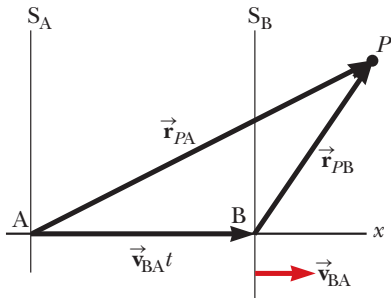
## Newton I (another way to state it)

If an object does not interact with other objects, it is possible to identify a reference frame in which the object has zero acceleration. This is an inertial reference frame.

A zero-acceleration reference frame is called an *inertial reference frame*.

## Different Observers

Observer  $B$  is moving with velocity  $\vec{v}_{BA}$  relative to observer  $A$ . Suppose observer  $A$  sees the particle  $P$  at rest. Observer  $B$  sees it moving, with velocity  $-\vec{v}_{BA}$ .



Both agree that Newton's first law holds for  $P$ !

# Newton's First Law Implications

**Question**<sup>1</sup> Which of the following statements is correct?

- I. It is possible for an object to have motion in the absence of forces on the object.
- II. It is possible to have forces on an object in the absence of motion of the object.

- A** I. only
- B** II. only
- C** Neither I. or II.
- D** Both I. and II.

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<sup>2</sup>Serway & Jewett, Physics for Scientists and Engineers, p114.



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# Summary

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- net force
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## Homework

Walker Physics:

- Read ahead in **Ch 5**.